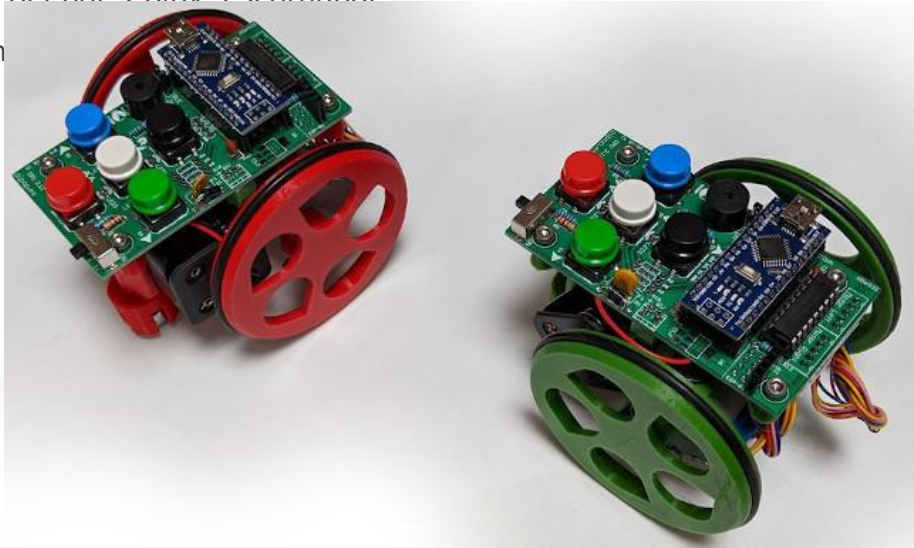


# Robótica para infantil

Se puede hacer un robot tipo Beebot, Colby, Escornabot  
Si no conocéis estos robots m



Podemos cargar el siguiente programa, modificado de [https://github.com/arduino/arduino-alvik-mpy/blob/main/examples/touch\\_move.py](https://github.com/arduino/arduino-alvik-mpy/blob/main/examples/touch_move.py)

```
from arduino_alvik import ArduinoAlvik
from time import sleep_ms
import sys

alvik = ArduinoAlvik()
alvik.begin()

alvik.left_led.set_color(1, 0, 0)
alvik.right_led.set_color(1, 0, 0)

distancia = 15

movements = []
```

```
def blink():
    alvik.left_led.set_color(1, 0, 1)
    alvik.right_led.set_color(1, 0, 1)
    sleep_ms(200)
    alvik.left_led.set_color(1, 0, 0)
    alvik.right_led.set_color(1, 0, 0)

def add_movement():
    global movements

    if alvik.get_touch_up():
        movements.append('forward')
        blink()
        while alvik.get_touch_up():
            sleep_ms(100)
    if alvik.get_touch_down():
        movements.append('backward')
        blink()
        while alvik.get_touch_down():
            sleep_ms(100)
    if alvik.get_touch_left():
        movements.append('left')
        blink()
        while alvik.get_touch_left():
            sleep_ms(100)
    if alvik.get_touch_right():
        movements.append('right')
        blink()
        while alvik.get_touch_right():
            sleep_ms(100)
    if alvik.get_touch_cancel():
        movements = []
        for i in range(0, 3):
```

```
val = i % 2
alvik.left_led.set_color(val, 0, 0)
alvik.right_led.set_color(val, 0, 0)
sleep_ms(200)
while alvik.get_touch_cancel():
    sleep_ms(100)
```

```
def run_movement(movement):
    if movement == 'forward':
        alvik.move(distancia, blocking=False)
    if movement == 'backward':
        alvik.move(-distancia, blocking=False)
    if movement == 'left':
        alvik.rotate(90, blocking=False)
    if movement == 'right':
        alvik.rotate(-90, blocking=False)
    while not alvik.get_touch_cancel() and not alvik.is_target_reached():
        alvik.left_led.set_color(1, 0, 0)
        alvik.right_led.set_color(1, 0, 0)
        sleep_ms(100)
        alvik.left_led.set_color(0, 0, 0)
        alvik.right_led.set_color(0, 0, 0)
        sleep_ms(100)
```

```
while alvik.get_touch_ok():
    sleep_ms(50)
```

```
while not (alvik.get_touch_ok() and len(movements) != 0):
    add_movement()
    sleep_ms(50)
```

```
try:
    while True:
        alvik.left_led.set_color(0, 0, 0)
        alvik.right_led.set_color(0, 0, 0)
```

```
for move in movements:
```

```
    run_movement(move)
```

```
    if alvik.get_touch_cancel():
```

```
        break
```

```
movements = []
```

```
while not (alvik.get_touch_ok() and len(movements) != 0):
```

```
    alvik.left_led.set_color(1, 0, 0)
```

```
    alvik.right_led.set_color(1, 0, 0)
```

```
    alvik.brake()
```

```
    add_movement()
```

```
    sleep_ms(100)
```

```
except KeyboardInterrupt as e:
```

```
    print('over')
```

```
    alvik.stop()
```

```
    sys.exit()
```

El resultado es que perfectamente se puede usar como robótica en infantil

Los robots Beebot, Colby, Escornabot. utilizan la distancia de 15cm de desplazamiento, justo lo mismo que los palos depresores de lengua, luego fácilmente uno puede hacer un circuito :

<https://www.youtube.com/embed/h8wAwcPxYL0>

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Revision #2

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