

Control de Motores

Se trata que el robot haga la siguiente secuencia de movimiento de forma indefinida:

- Adelante durante 1 segundo.
- Derecha durante 1 segundo.
- Izquierda durante 1 segundo.
- Atrás durante 1 segundo.



The image shows a Scratch script for controlling a robot's movement. It starts with an 'al iniciar' (when green flag clicked) block. The main logic is contained within a 'para siempre' (forever) loop. The sequence of actions in the loop is: 1. Motor 'ambos' (both) moving 'avanzar' (forward) at 'velocidad' 255. 2. 'pausa (ms)' 1000. 3. Motor 'izquierdo' (left) moving 'avanzar' (forward) at 'velocidad' 255. 4. Motor 'derecho' (right) moving 'avanzar' (forward) at 'velocidad' 0. 5. 'pausa (ms)' 1000. 6. Motor 'izquierdo' (left) moving 'avanzar' (forward) at 'velocidad' 0. 7. Motor 'derecho' (right) moving 'avanzar' (forward) at 'velocidad' 255. 8. 'pausa (ms)' 1000. 9. Motor 'ambos' (both) moving 'retroceder' (backward) at 'velocidad' 255. 10. 'pausa (ms)' 1000.

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